

Dijkstra's Algorithm

Find, for a given source vertex, the shortest path to every destination. path w/ least total weights of edges

Function $sssp(g, src)$:

frontier \leftarrow new MinHeap

frontier.insert(0, src)

cost \leftarrow new Dictionary

cost.insert(src, 0)

\rightarrow While frontier is not empty:

currentCost \leftarrow frontier.peekPriority()

current \leftarrow frontier.remove()

\rightarrow For each neighbor of current:

If neighbor is not a key in cost:

cost.insert(neighbor, currentCost + weight)

frontier.insert(currentCost + weight, neighbor)

Else If cost.get(neighbor) > currentCost + weight:

cost.update(neighbor, currentCost + weight)

frontier.insert(currentCost + weight, neighbor)

EndIf

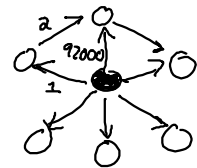
EndFor

EndWhile

Return cost

End Function

When a vertex is removed: if this is the first time we've explored it, it will have the lowest cost possible to reach it.



$O(E)$

$f(n)$ is $O(g(n))$

$g(n) \leq h(n)$

$f(n)$ is $O(h(n))$

$E \leq V^2$

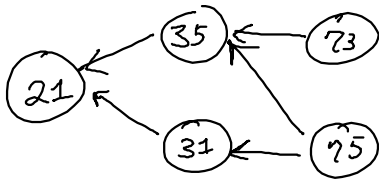
$O(E \cdot \log E)$

$O(E \cdot \log V^2) = O(E \cdot 2 \log V)$

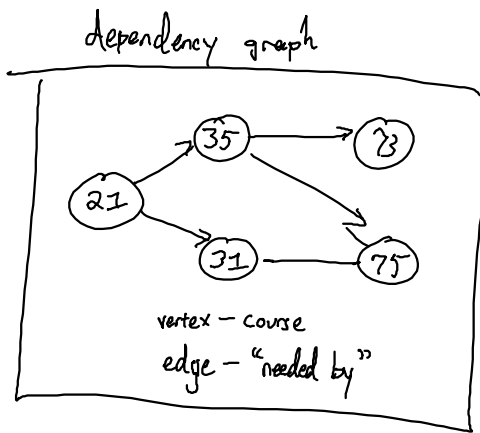
$= O(E \cdot \log V)$

$O(V^2)$

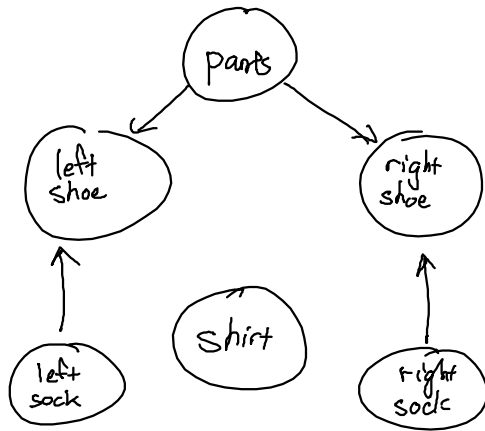
Topological Sort



vertex - course
edge - "depends on"



vertex - course
edge - "needed by"



Topological sort of a graph:
a sequence of vertices such that, if
the edge $\langle V_1, V_2 \rangle$ is in the graph,
 V_1 appears before V_2 in the sequence.

While graph is not empty:
Find a vertex with in-degree of zero
Add it to the result list
Remove it (and all of its outgoing edges) from graph

21, 31, 35, 75, 73
21, 35, 73, 31, 75

Function Toposort(g):

For each vertex in g
Explore(g , vertex)

EndFor

EndFunction

Function Explore(g , vertex):

If vertex is finished, return

If vertex is exploring, \uparrow

Mark vertex as exploring

For each neighbor:

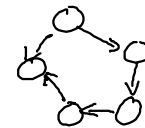
Explore(g , neighbor)

EndFor

Add vertex to the beginning of answer

Mark vertex as finished

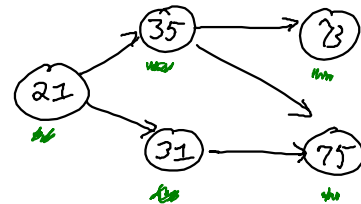
EndFunction



• Unexplored

• Exploring

• Finished



21, 31, 35, 75, 73



Minimum Spanning Tree

Prim's Algorithm

- Start at any vertex
- Add an edge which is cheapest among those which connect a new vertex into existing network
- Repeat until network connected

