

Reminder: vote!

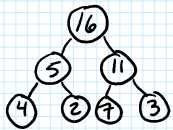
TODAY

- HEAPSORT & analysis of heapify
- review Dictionary
 - ADT
 - BST implementation
 - AVL implementation
- new Dictionary implementation: hash table

USING A HEAP TO SORT

We can use a max heap to get a list of elements in sorted order!

example



We want the output: 16, 11, 7, 5, 4, 3, 2

to get this: `while(!pq.isEmpty()) // n iterations`
`cout << pq.remove() << endl; // O(log2 n)`

runtime: $O(n \log_2 n)$

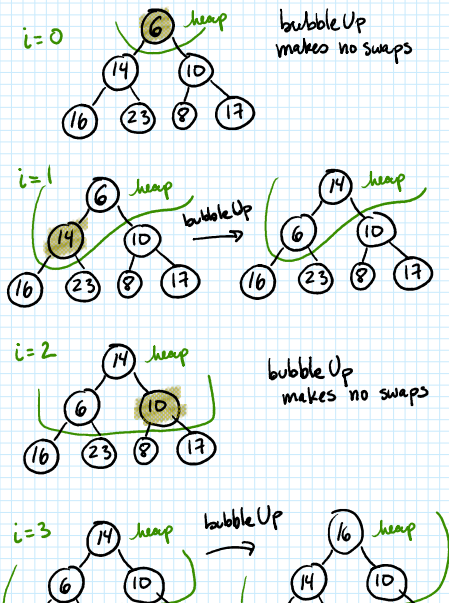
The same runtime as mergesort! Also, heapsort is in place (no extra memory).

HEAPIFY: a technique to take a vector and turn it into a heap

Two options:

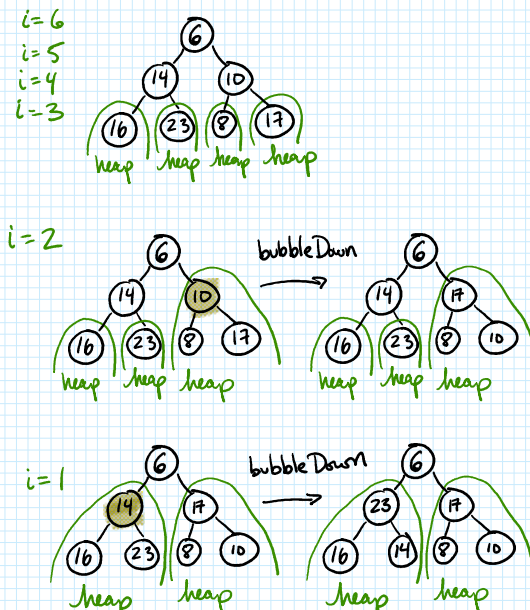
① void heapify(vector, size)
 for i = 0 to size-1
 bubbleUp(i)

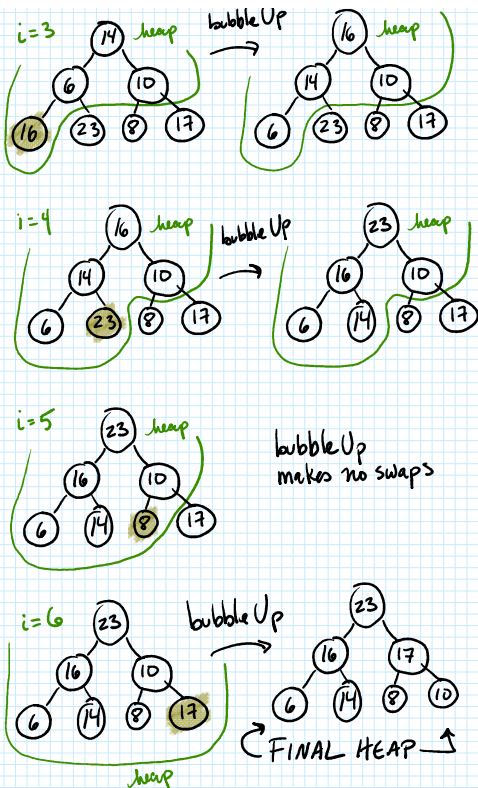
Idea: The root is a heap.
 Add one element to heap in each iteration.



② void heapify(vector, size)
 for i = size-1 to 0
 bubbleDown(i)

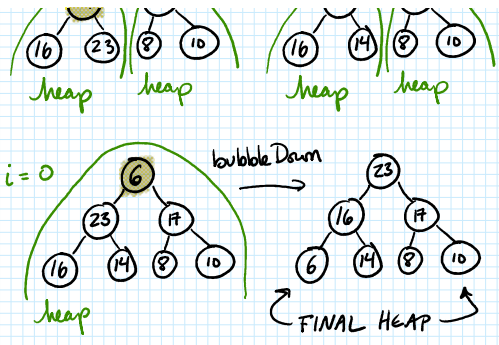
Idea: Each leaf is a heap.
 We merge them together.





There are n elements so we run bubbleUp n times. Each bubbleUp is $O(\log_2(n))$.

Overall cost of heapify version 1: $O(n \log_2(n))$



How much work does heapify version 2 take?

There are $O(\frac{n}{2})$ leaves in a complete tree.
 If each leaf is its own heap, zero work to bubble Down. } $\frac{n}{2} \cdot 0$
 For the next level just before the leaves, there are $n/4$ nodes. } $\frac{n}{4} \cdot 1$
 We do at most 1 swap for each of these bubble Downs.
 For the next level: $n/8$ nodes } $\frac{n}{8} \cdot 2$
 at most 2 swaps in each bubble Down.

$$\begin{aligned} \text{total work} &= \sum_{i=0}^{\log_2 n} \text{work at level } i \\ &= \sum_{i=0}^{\log_2 n} (\# \text{ nodes at level } i) \cdot (\text{work per node at level } i) \\ &= \sum_{i=0}^{\log_2 n} \left(\frac{n}{2^{i+1}} \right) \cdot i \\ &= n \sum_{i=0}^{\log_2 n} \frac{i}{2^{i+1}} \end{aligned}$$

← this matches the way we were counting work

taking the common factor n out in front of the sum

What is this sum?

$$\begin{aligned} \sum_{i=0}^{\infty} \frac{i}{2^{i+1}} &< \sum_{i=0}^{\infty} \frac{i}{2^{i+1}} \quad \text{because adding more terms to } \infty \text{ only makes the sum bigger} \\ &= \frac{0}{2} + \frac{1}{2} + \frac{2}{4} + \frac{3}{8} + \dots \quad \text{expanding the sum} \\ &= \frac{1}{2} + \frac{1}{4} + \frac{1}{4} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \dots \quad \text{separating the fractions} \\ &= \left(\frac{1}{2} + \frac{1}{4} + \frac{1}{8} + \dots \right) + \left(\frac{1}{4} + \frac{1}{8} + \dots \right) + \left(\frac{1}{8} + \dots \right) + \dots \quad \text{grouping and reordering} \\ &= 1 + \frac{1}{2} + \frac{1}{4} + \dots \quad \text{by math fact: } \sum_{i=1}^{\infty} \frac{1}{2^i} = 1 \quad \text{used a bunch of times} \\ &= 1 + \left(\frac{1}{2} + \frac{1}{4} + \dots \right) \quad \text{regrouping} \\ &= 2 \quad \text{by math fact again} \end{aligned}$$

So overall cost of heapify version 2 is $< 2n$.
 $O(n)$ ← we prefer version 2!

HEAPSORT algorithm

- start with unsorted array of n elements
- heapify it
- extract the max elements one at a time

the DICTIONARY ADT (review)

templated with k = key type and v = value type

```

void insert(k, v)
v get(k)
v remove(k)
void update(k, v)
bool contains(k)
bool isEmpty()
int getSize()
vector<k> getKeys()
vector<pair<k, v>> getItems()
  
```

example application: Instagram
 key: username
 value: all your data

operations	BST	AVL
insert	$O(h)$	$O(\log_2(n))$
remove	where	because
contains	h = height of tree	tree is guaranteed to be balanced
get	worst case $h = O(n)$	

Q: Arrays have $O(1)$ access. Can we use that to efficiently implement Dictionaries?

IMPLEMENTING DICTIONARIES AS ARRAYS

Main idea: we'll trade space for efficiency (use more memory, but run operations quickly)

Pro: arrays have $O(1)$ access

BUT: need to figure out how to take a (key, value) and decide where to put it in the array

A mapping of key \rightarrow array index is called a **HASH FUNCTION**.

An array organized this way is called a **HASH TABLE**.

example: Keys of type int

- already might be a valid array index

- if too big, we need to map the key to a valid index

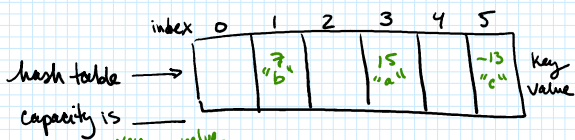
int hash(int key, int capacity)

int index = key % capacity // mod operator: just the remainder after division
works on both positive & negative numbers

if index < 0:

index += capacity // to fix up negative numbers

return index



insert(15, "a")

hash(15, 6) returns 3

insert(7, "b")

hash(7, 6) returns 1

insert(-13, "c")

hash(-13, 6) returns 5

insert(13, "d")

hash(13, 6) returns 1

Problem!

If two keys hash to the same index, it is a COLLISION.

We'll need to deal with collisions.

example: Keys of type string

We want a hash function: string \rightarrow int

Key "Ika"

in ASCII, each character corresponds to a number

Key "dog"

'd' = 48

'o' = 65

'g' = 97

Key "akI"

'a' = 49

'k' = 66

'I' = 98

...

'c' = 67

...

'q' = 57

...

...

'z' = 90

...

'z' = 122

Idea: add up the ASCII values of all letters

int hash(string key, int capacity)

int total = 0

for i = 0 to length of key

total *= 7 // prime number is a good choice

total += ASCII value of key[i]

return total % capacity

'I' = 73

'k' = 107

'a' = 97

hash("Ika", capacity) = 277 % capacity

hash("akI", capacity) = 277 % capacity

Proposal to reduce collisions:

use a multiplier based on letter position

HASH TABLE VOCABULARY

capacity — the number of available locations

size — the number of key-value pairs currently in the table

collision - occurs when multiple keys hash to the same index

load factor = $\frac{\text{size}}{\text{capacity}}$ } a float which measures how full the hash table is

HOW TO DEAL WITH COLLISIONS: TWO TECHNIQUES

① PROBING: if this index is already full, just look for the next empty spot to add pair

index →	0	1	2	3	4
hash table		6 "a"	16 "b"	8 "c"	11 "d"
filled?	false	true	true	true	true

example

```

insert(6, "a")      6 % 5 = 1
insert(16, "b")    16 % 5 = 1 // collision
insert(8, "c")     8 % 5 = 3
insert(11, "d")    11 % 5 = 1 // collision
    
```

```

V get (k, key)
int index = hash(key, capacity)
for (i = 0; i < capacity; i++)
    if array[index] is filled
        if array[index]'s key == key
            return array[index]'s value
        else
            index = (index + 1) % capacity
    else
        throw error: key not found in table
    
```

remove(16) will do:
 hash(16, 5) returns 1
 probe 1, 2 find it at index 2
 remove it

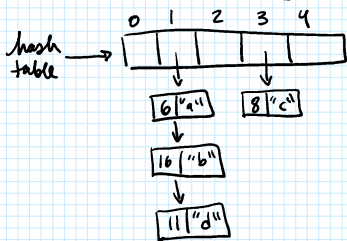
index →	0	1	2	3	4
table		6 "a"	16 "b"	8 "c"	11 "d"
filled?	false	true	false	true	true

get(11) will do:
 hash(11, 5) returns 1
 probe index 1, not found
 index 2, not filled, throw error

ISSUE: probe finds a gap, but when 11 was inserted, that was not a gap.
 Note: we could fix this with more complicated bookkeeping, but it will be tricky to implement.

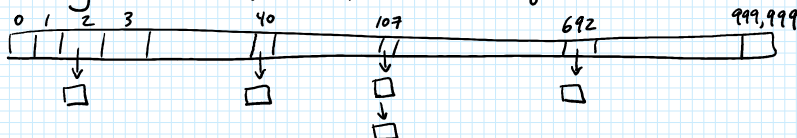
DEALING WITH COLLISIONS, AN ALTERNATE TECHNIQUE

② CHAINING: every spot in the hash table points to a linked list, not a single item



To implement "get", we should
 - hash to correct index
 - do a linear search of that chain

As long as the hash function spreads out the keys, each chain should be short:



We are wasting space in order to save time.

We will track the load factor ($\text{size}/\text{capacity}$) after every insert, and increase the capacity when the load factor gets high.

Overall, these assumptions will make all Dictionary

insert/get/remove/contains operations really fast: $O(1)$

* $O(1)$ amortized
because we might need to resize

* ASSUMPTIONS

- hash function spreads out keys really well
- we're ok with using lots of space