

CS41 Lab 13: Approximation Algorithms

December 8 2022

This week, we'll continue exploring NP-COMPLETE decision problems, and develop approximation algorithms for related versions of those problems.

1. **Traveling Salesman Problem.** In this problem, a salesman travels the country making sales pitches. The salesman must visit n cities and then return to her home city, all while doing so as cheaply as possible.

The input is a complete graph $G = (V, E)$ along with nonnegative edge costs $\{c_e : e \in E\}$. A *tour* is a simple cycle $(v_{j_1}, \dots, v_{j_n}, v_{j_1})$ that visits every vertex exactly once.¹ The goal is to output the minimum-cost tour.

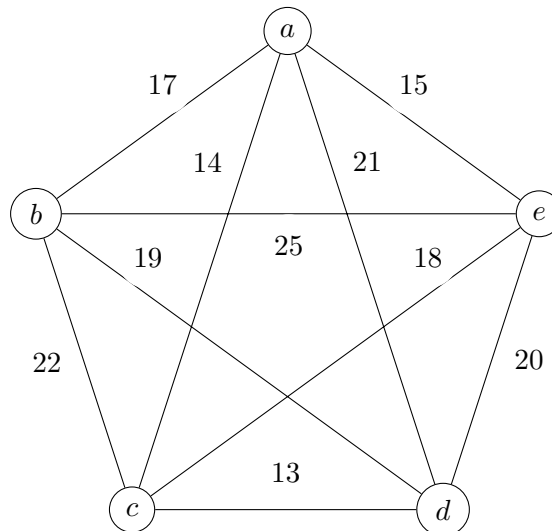
For many TSP applications (such as when the cost is proportional to the distance between two cities), it makes sense for the edges to obey the *triangle inequality*: for every i, j, k , we have

$$c_{(ik)} \leq c_{(ij)} + c_{(jk)}.$$

This version is often called METRIC-TSP.

The (decision version of the) Traveling Salesman Problem is NP-COMPLETE. For this problem, you will develop a 2-approximation algorithm for METRIC-TSP.

- (a) First, to gain some intuition, consider the following graph:



- (b) *On your own* try to identify a cheap tour of the graph.
- (c) Build some more intuition by computing the minimum spanning tree (MST) of the graph. Let T be your minimum spanning tree.
- (d) Let OPT be the cheapest tour. Show that its cost is bounded below by the cost of the MST: $\text{cost}(T) \leq \text{cost}(OPT)$.

¹except for the start vertex, which we visit again to complete the cycle

- (e) Give an algorithm which returns a tour A which costs at most twice the cost of the MST: $\text{cost}(A) \leq 2 \text{cost}(T)$.
- (f) Conclude that your algorithm is a 2-approximation for METRIC-TSP.

2. **Toy-Storage.** William has lots of toys of all different sizes. You'd like to purchase a number of bins in which to store the toys. Approximately how many bins will you need?

Let's formalize the TOY-STORAGE problem as follows. Suppose there are n toys, with sizes s_1, \dots, s_n , with $0 < s_i < 1$ for all i . Assume each bin has size 1 and can hold any collection of toys whose total size is less than or equal to 1.

In this problem, you'll develop a greedy approximation algorithm, which works by taking each toy in turn and placing it into the first bin that can hold it. Let $S := \sum_{i=1}^n s_i$.

- (a) Show that the optimal number of bins is at least $\lceil S \rceil$.
- (b) Show that the greedy algorithm leaves at most one bin half full.
- (c) Prove that the number of bins used by the greedy algorithm is at most $\lceil 2S \rceil$.
- (d) Prove that the greedy algorithm is a 2-approximation algorithm for the TOY-STORAGE problem.